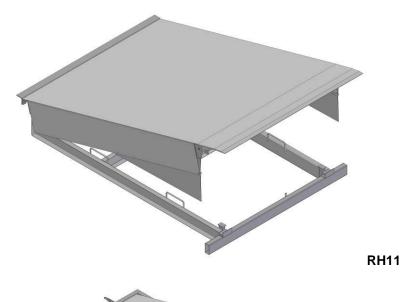


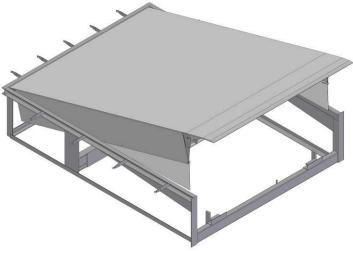
Loading Bays • Dock Shelters • High-Speed Doors
Fire Doors • Free Standing Frames and Dock Houses • Scissor Lifts
Loading Bridges • Industrial Doors



Instructions manual Hydraulic dock leveller Models: RH11 and RH12

EMBEDDED AND SELF-SUPPORTING





RH12

01 - Introduction	3
02 - Technical specifications	4
02.01 – Usage conditions and limits	4
02.02 – RH11 embedded pit	4
02.03 – RH12 self-supporting pit	
02.04 – Platform	
02.05 – Lip	5
02.06 – Bedplate	
02.07 – Hydraulic power unit	
02.07.01 – Hydraulic unit version 03	
02.07.02 – Hydraulic unit version 07	
02.08 – Electrical control panel	
02.09 – Safety systems	
02.10 – Maintenance	
02.10.01 – Hydraulic oil	
02.10.02 – Grease points	
02.10.03 – Dock leveller descent speed regulation	
02.10.04 – Lip opening speed	
02.10.05 – Maintenance plan	
02.11 – Instructions for use	9
02.11.01 – Before use	
02.11.02 – During use	10
02.11.03 – After use	
02.11.04 – Precautions during use	10
03 – CE Declaration	11
04 – Machine units and parts	12
05 – Installation	
05.01 – Positioning in the pit	14
05.01 – Positioning in the pit	14 14
05.01 – Positioning in the pit	14 14 14
05.01 – Positioning in the pit	14 14 14
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	
05.01 – Positioning in the pit	14
05.01 – Positioning in the pit 05.02 – Securing the leveller in the pit 05.02.01 – Securing in the case of an embedded model 05.02.02 – Securing in the case of a self-supporting model 05.03 – Installing the electrical control panel 05.04 – Completed installation 05.05 – Electrical control panel connection 05.05.01 – Connecting the power input 05.05.02 – Motor input connection 05.05.03 – Electro valves connection 05.05.04 – Description of the connection terminals 05.05.05 – Actions Selection 05.05.06 – Timers 05.05.07 – Operation 05.05.08 – Accessories 05.05.09 – Characteristics 06 – Dismantling 06.01 – Dismantling an embedded leveller 06.02 – Dismantling a self-supporting leveller	14
05.01 – Positioning in the pit 05.02 – Securing the leveller in the pit 05.02.01 – Securing in the case of an embedded model 05.02.02 – Securing in the case of a self-supporting model 05.03 – Installing the electrical control panel 05.04 – Completed installation 05.05 – Electrical control panel connection 05.05.01 – Connecting the power input 05.05.02 – Motor input connection 05.05.03 – Electro valves connection 05.05.04 – Description of the connection terminals 05.05.05 – Actions Selection 05.05.06 – Timers 05.05.07 – Operation 05.05.08 – Accessories 05.05.09 – Characteristics 06 – Dismantling 06.01 – Dismantling an embedded leveller 06.02 – Dismantling a self-supporting leveller 07 – Incidents	
05.01 – Positioning in the pit	14
05.01 – Positioning in the pit 05.02 – Securing the leveller in the pit 05.02.01 – Securing in the case of an embedded model 05.02.02 – Securing in the case of a self-supporting model 05.03 – Installing the electrical control panel 05.04 – Completed installation 05.05 – Electrical control panel connection 05.05.01 – Connecting the power input 05.05.02 – Motor input connection 05.05.03 – Electro valves connection 05.05.04 – Description of the connection terminals 05.05.05 – Actions Selection 05.05.06 – Timers 05.05.07 – Operation 05.05.08 – Accessories 05.05.09 – Characteristics 06 – Dismantling 06.01 – Dismantling an embedded leveller 06.02 – Dismantling a self-supporting leveller 07 – Incidents	14
05.01 – Positioning in the pit. 05.02 – Securing the leveller in the pit. 05.02.01 – Securing in the case of an embedded model. 05.02.02 – Securing in the case of a self-supporting model. 05.03 – Installing the electrical control panel. 05.04 – Completed installation. 05.05 – Electrical control panel connection. 05.05.01 – Connecting the power input. 05.05.02 – Motor input connection. 05.05.03 – Electro valves connection. 05.05.04 – Description of the connection terminals. 05.05.05 – Actions Selection. 05.05.06 – Timers. 05.05.07 – Operation. 05.05.08 – Accessories. 05.05.09 – Characteristics. 06 – Dismantling. 06.01 – Dismantling an embedded leveller. 06.02 – Dismantling a self-supporting leveller. 07.01 – The panel DOES NOT light up. 07.02 – The ramp DOES NOT rise. 07.03 – The leveller DOES NOT descend.	14
05.01 – Positioning in the pit	14

01 - Introduction

This manual is a guide for the correct, safe installation, use and maintenance of the RH11 and RH12 dock levellers.

Compliance with the instruction set forth herein ensures the long life of the machine and respect for the safety guidelines prevents the most common work or maintenance-related accidents.

The instructions in this manual do not, in themselves, guarantee safe working and do not release operators from their obligation to observe the safety code, legislation or local or national regulations.

The service rule set out in this manual is only valid for mobile ramps and for loading and unloading trucks.

In the event of mislaying the instructions and maintenance manual, another copy that is specific for the machine should be requested. It is essential and absolutely necessary to keep this manual with the machine, in order to consult it at any time, or settle any doubts regarding its use.

The manufacturer has no direct control over the operations, locations or maintenance of the machine. Operators are responsible for using best safety and maintenance practices.

Operators have the obligation to read and make sure they understand this manual before they use the machine.

Using the machine with caution and adequate training not only protects the operator but also the people who depend on his work.

The information set out in the manual is valid at the time of publication.

The photographs and drawings are generic; as a result, this information may be changed, due to the constant development and research carried out by *INKEMA*.

In the event of discrepancy, please consult the technical department.

The manual is an inseparable part of the machine and must be kept with it in the event of sale.

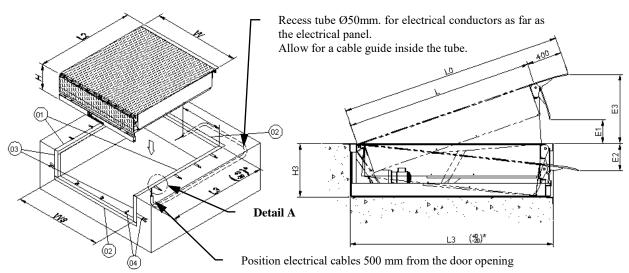
02 - Technical specifications

Ramp designed pursuant to the **UNE-EN 1398** standard Calculated for a maximum nominal load of: (See its plate characteristics)

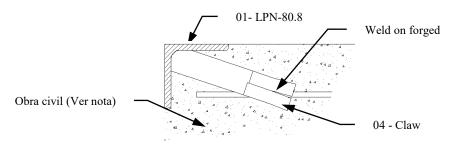
02.01 - Usage conditions and limits

- Nominal load capacity 6t
- Motor electrical voltage 230/400 volt. 3F 50Hz
- Motor electrical power 0.75 Kw.
- Electrical output voltage to emergency electro valve 24 volt. AC.
- Max. operating pressure of the hydraulic circuit 140 kg/cm² (Bar)
- Operating temperature range (-10°C +40°C)
- Noise level generated <70db
- Max. transit speed 10Km/h
- Max. operating gradient 12.5% (7°)
- Do not work with the machine while the emergency stop is activated or if the power supply has been cut off.

02.02 - RH11 embedded pit



(*) Pit tolerance



Detail A of subframe

Note: Metal profile joints with continuous cord and a neck of 6mm Floor of at least H250 concrete with a thickness greater than or equal to 200mm

PIT FRAME

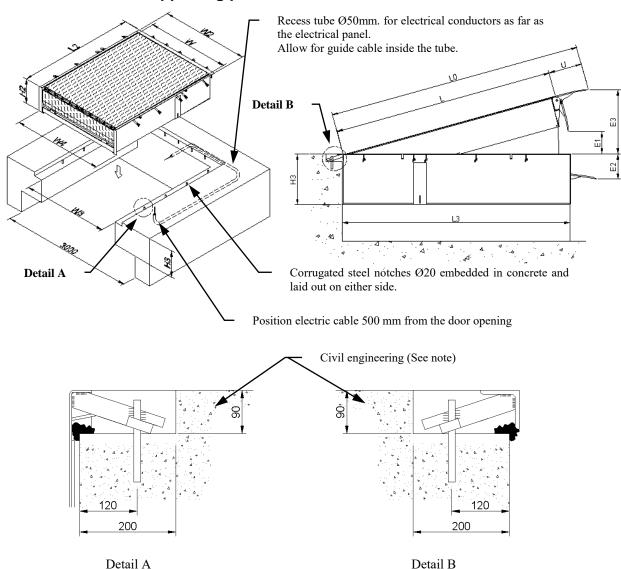
01	02	03	04
2 un.	2 un.	(1+1) Un. **	15 un. **
LPN-80.8 x (L3 – 10)	LPN-80.8 x (W3 + 160)	LPN-80.8 x H3	#3x40x200

^(**) Parts with some type of machining (Ask the Technical Department for drawings)



The diagonals of the pit must be equal ± 5 mm

02.03 - RH12 self-supporting pit



Note: Metal profile joints with continuous cord and a neck of 6mm Floor of at least H250 concrete with a thickness greater than or equal to 200mm.

02.04 - Platform

- Superior tear plate (thickness 6/8mm.), quality ST-37.
- 10 cold rolled profiles
- 2 cold rolled lateral profiles (non-shear safety panels).
- Front hinge unit (lip joint).
- Rear hinge unit (platform joint).
- Safety bar for executing maintenance work.

02.05 - Lip

- Tear plate (thickness 13/15mm.), quality ST-37.
- Press stroke 5° 150mm. from the end (for perfect adjustment to the truck).
- Milled at the end (to ease the passage of the fork-lift trucks).

02.06 - Bedplate

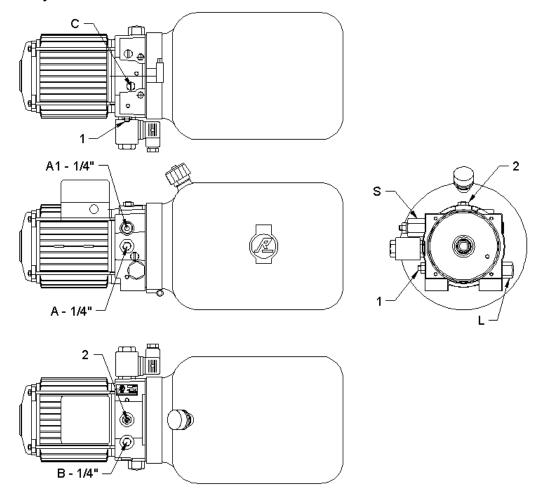
- Rear assembly (head) formed by rolled profiles.
- Front assembly with profiles for supporting the lip.
- Side profiles joining the front assembly with the rear assembly.
- The movements of the platform and lip are executed through an electro hydraulic unit.

02.07 - Hydraulic power unit

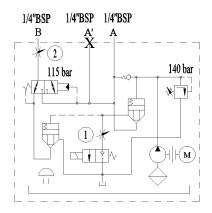
- 1.0CV electric motor. 0'75kw 230/400Volt 3F 50Hz.
- Hydraulic pump with flowrate of 5 litres/minute.
- 7-litre tank with oil level viewer.
- Logicblock where all the elements are incorporated (including 24V electro valve).
- Ø50mm. cylinder with rod for raising platform and parachute safety valve.
- 1 Ø30mm. cylinder with rod for lip raising.
- Leads, connection fittings, etc...

The machine may be supplied with any of the following hydraulic unit versions, both are identical and perform the same function.

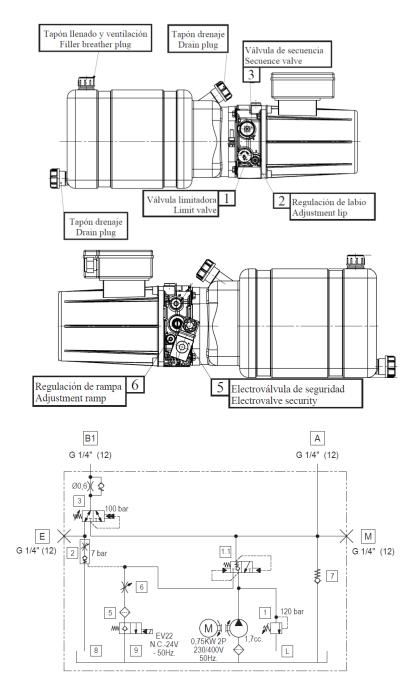
02.07.01 - Hydraulic unit version 03



- 1 Leveller regulation
- 2 Lip regulation
- A Lift cylinder
- A1 Lift cylinder
- B Lip cylinder
- C Screw and spring
- L Limit valve
- S Sequence valve



02.07.02 - Hydraulic unit version 07



02.08 - Electrical control panel

(See electrical control panel connections, page 17)

- Transformer for manoeuvring circuit at 24Volt. AC.
- Green light indicating ON.
- Emergency stop/section switch.
- Thermal switch.
- Fuses.
- Terminal block.
- Box 190X*240Y*105Z (IP-55)

02.09 - Safety systems

- Emergency and/or power failure electro valve
- Emergency stop/section switch.
- Elevation cylinder safety valve
- Toe guards

• Non-slip surface

02.10 - Maintenance

The correct operation and long life of the ramp depend largely on the preventive maintenance work carried out.

Advanced maintenance may only be carried out by the **INKEMA** technical service or staff authorised by the latter.

This maintenance is carried out to ensure that the product conserves the safety and usage characteristics it had when it was first installed.

All changes, repairs or manipulation of the product that fail to comply with these regulations will lead to the cancellation of the one-year warranty term and the liability of **INKEMA** for the product will automatically end.

Continuous greasing, painting and vigilance is the best way to guarantee its performance for many years.

02.10.01 - Hydraulic oil

The hydraulic oil must be replaced every two years.

The oil must contain agents that prevent the formation of foam, oxidation and water absorption. If the winter temperatures are very low, the oil must not be too thick and its viscosity index must remain stable at low temperatures.

Never mix different oils, as the new oil may have a different resistance to oxidation and affect the life of the original oil.

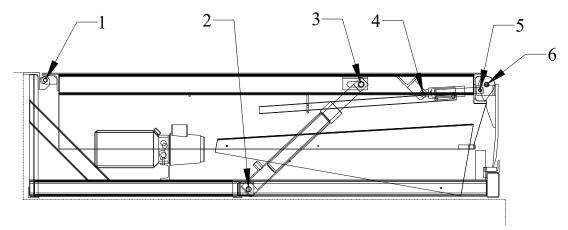
It is important to check the oil level every 6 months. The oil tank must be filled until it almost overflows from the closing cap, in the lowest possible position.

The machine is supplied already containing **T-15 oil**

Hydraulic oil for ramps in refrigerated storerooms must have specific properties of use, in accordance with the temperatures to which it is exposed. For this reason, if the need arises, the manufacturer must be informed about the conditions in which the machine will be operating to ensure it contains the special oil.

02.10.02 - Grease points.

Every six months, check the grease points shown in the diagram



02.10.03 - Dock leveller descent speed regulation

The speed will be regulated using the respective adjuster (1). (See hydraulic unit, page 6)

02.10.04 - Lip opening speed

The lip opening/closing speed is determined in the factory, but can be regulated using the respective adjuster (2). (See hydraulic unit, page 6)

02.10.05 - Maintenance plan

Maintenance job	Daily	Every month	6 months	1 year	2 years
General state of the machine	*	*	•	*	*
Greasing			•	*	*
Hydraulic oil level			•	*	*
Oil leak inspection			*	•	*
Weld inspection				•	*
Axle inspection				•	*
Inspection of lateral adhesive bands				•	*
Paint inspection				•	*
Flexible conduits and connection fittings				•	*
Manoeuvring speed				•	*
Check parachute valve					*
Change hydraulic oil					*

02.11 - Instructions for use

02.11.01 - Before use

Make a visual check to ensure the leveller is in perfect conditions of use.

Centre the vehicle against the rubber stops of the leveller.

Check that the vehicle is completely immobilised and blocked. (Switch off the engine, apply the handbrake and place chocks on the wheels).

To raise the leveller to the load surface level, connect the manoeuvring circuit by turning the red section switch. The green pilot light will come on.

To raise the leveller and open the lip, press the elevation button without releasing it.

If you stop pressing the button, the leveller will descend at a controlled speed, due to its own weight.

Raise the leveller until the lip starts to open. Once the lip is open completely, release the elevation button.

Let the leveller descend at a steady speed until it rests on the load surface of the truck.



Check that the whole width of the lip is resting on the load surface of the vehicle in an area NO smaller than 130mm.

02.11.02 - During use

The dock leveller will merely rest on the load surface (truck). The hydraulic cylinders MUST NOT be blocked to allow the leveller to adapt to the height of the load surface (which will vary, depending on the variation in the truck suspension).

Check that the emergency stop is NOT activated and that the leveller is supplied with power.

VERY IMPORTANT:

It is strictly prohibited to perform loading and unloading operations with the emergency stop activated, or while the leveller is not supplied with power.

Never exceed the maximum nominal load. (See its plate characteristics).

Ensure that the leveller continues to rest on the load surface during transit. If this is not the case, press the emergency stop button immediately.

Fork-lift trucks must be driven with caution. The maximum transit speed calculated for the leveller is 10 km/hour.

02.11.03 - After use

Raise the leveller and close the lip before the truck leaves the loading position. To do this, press the elevation button and raise the leveller just enough for it to clear the truck.

Release the button and wait for the leveller to descend at a steady speed and rest on the closed lip on the front of the bedplate.

02.11.04 - Precautions during use

Check that the emergency stop is not activated.

Never exceed the maximum nominal load. (See its plate characteristics).

Before each manoeuvre check that no-one is in the working area.

Check that the leveller is resting properly on the load surface of the truck, with the entire lip coupled to a surface of approximately 130 mm along its whole width.

The hydraulic unit has the sole function of making the necessary movements to manipulate only the dock leveller. It must never be used to support and/or lift loads.

Before raising the device ensure that its movement is not blocked by other equipment. (Doors, etc...)

After completing the operation check that the lip is properly inserted in the closed leveller position.

03 - CE Declaration



DECLARATION OF CONFORMITY

INKEMA SISTEMAS, S.L. declares, under its own responsibility, that the electro hydraulic dock levellers:

Make : INKEMA

Model : **RH11** and **RH12** with a capacity of **6000** $\mathbf{Kg}^{(*)}$

Year of manufacture: 2016

Are compliant with the essential requirements of the following directives:

2006 / 42 / EC Machine safety.

2004 / 108 / EC Electromagnetic compatibility.

2006 / 95 / EC Low voltage.

And have been calculated and designed pursuant to the following European standards:

EN 1398:2010 Dock levellers

EN ISO 12100-1:2010 Machine safety. Basic concepts. General design principles.

Electromagnetic compatibility. Basic immunity concepts for

industrial environments.

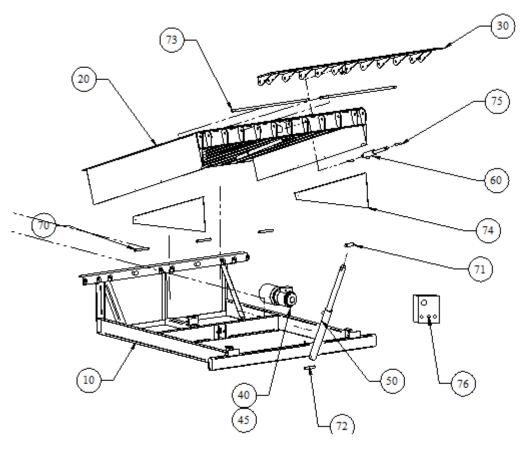
EN 61000-6-4:2011 Electromagnetic compatibility. Basic emissions concepts in

industrial environments.

EN 60204-1:2010 Machine safety – Electrical equipment – General provisions.

^(*) In the event that the capacity is other than 6000kg, the respective EC certificate will be attached to this manual.

04 - Machine units and parts



Pos.	Part code	Description
10	20.0002 (*)	6t RH bedplate (*)
20	20.0001 (*)	6t RH structure (*)
30	20.0003 (*)	6t RH swing lip (*)
40	20.0017.0001	RH hydraulic power unit (Complete)
40	30.0015.0005	400/230v 3F 1.0cv 3000rpm power unit motor
40	30.0011.0007	RH1 1.7cc/v hydraulic pump body
40	30.0011.0008	7 Lit. plastic tank for RH1 hydraulic power unit
40	30.0011.0009	RH1 power unit sliding safety electro valve
40	30.0011.0010	Safety electro valve coil for RH1 power unit
40	30.0011.0011	Electro valve coil electrical connector
45	30.0011.0001	Bonded washer 3/8"
45	30.0011.0002	M/M connection fitting thread 3/8" Zinced gas
45	30.0011.0014	M/M reducer connection fitting 3/8" to 1/4"
45	30.0011.0003	Hydr. flexible conduit 2 straight outputs 3/8" Gas L=700
45	30.0011.0004	Hydr. flexible conduit 1 straight output + 1 90° output 1/4" Gas L=1700
45	30.0011.0006	Hydraulic oil
45	30.0012.0009	Grower M10 DIN-7980 safety washer
45	30.0012.0010	M10x20 DIN-933 screw
50	30.0010(**)	Single effect cylinder, machine elevation
60	30.0010.0002	Single effect cylinder Ø30 e/c =260 run=105
70	30.0006.0007	Rear hinge axle Ø19 x 175
70	30.0012.0034	DIN-471 Seeger ring for axle with Ø19 / Ø17.5
71	30.0006.0059	Zinqued axle for mounting hole Ø30x103
72	30.0006.0011	Axle for cylinder Ø25x120
72	30.0012.0040	Ø5x40 DIN-94 Cotter Pin
73	30.0006 (*)	Lip axle (*)
73	30.0012.0040	Ø5x40 DIN-94 Cotter Pin

74	20,0009 (*)	Calv. mahila taa ayand
74	30.0008(*)	Galv. mobile toe guard
74	30.0012.0002	M6x16 ISO-7380 zinced Allen truss head cap screw
74	30.0012.0003	M6 DIN-985 zinced self-locking nut
75	30.0006.0008	Zinqued axle Ø16 x 70
75	30.0012.0039	Ø5x28 DIN-94 Cotter Pin
76	20.0018.0001	RH electrical panel (standard)
76	30.0015.0104	190X*240Y*105Z IP-55 plastic box for electrical panel
76	30.0013.0005	Electrical panel cover for doors
76	30.0015.0090	Telemecanique XB7-EA1P green push button
76	30.0015.0097	Telemecanique XB7-EV0.MP green pilot led
76	30.0015.0088	Telemecanique VN12 3-phase section switch
76	30.0015.0089	Telemecanique VN12 3-phase section switch control or handle
76	30.0015.0085	Electroniccard for ramps
76	30.0015.0103	Telemecanique GV2ME08 2.5-4Amagnetothermal motor guard
76	30.0015.0101	Ø5x20 1Amp 230v glass fuse
76	30.0015.0001	Black/Brown/Grey class 5 or 6 4x1.5 electrical hose
76	30.0015.0002	Black 2x1 Aceflex AG electrical cable
76	30.0015.0003	BGR M25 PG-9 tube with two sleeves.

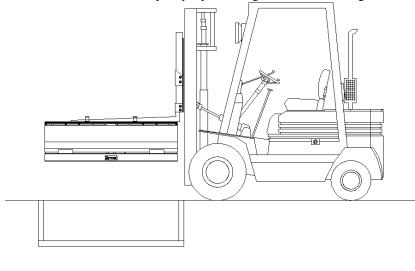
^(*) Specify the part code and description, and the machine model, dimensions and load. (**) Specify the part code and the machine model, dimensions and cylinder dimension.

05 - Installation

05.01 - Positioning in the pit

VERY IMPORTANT: When handling the leveller, always respect the occupation risk prevention legislation and the regulations regarding safety, hygiene and health at work.

Place it in the pit with the help of a crane, fork lift truck or similar element, using the worm screws, and chains, slings and similar items to lift it. With a load capacity equal to or greater than the weight of the leveller



Then unwind the electrical cable and pass it through the tube that is centred at the back the pit. Once the cable has emerged at the other end of the tube, position the leveller correctly in the pit.

05.02 - Securing the leveller in the pit

05.02.01 - Securing in the case of an embedded model

Once the leveller is in the pit, check the following:

The separation between the sides of the leveller and the pit must be exactly the same at the front and back of it.

In the event of the separation not being equal in the pit, this must be at the rear part and not at the sides.

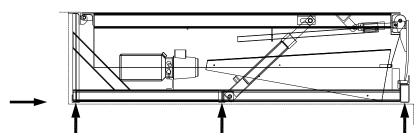
Considering that the height of the pit is usually about 10mm. more than the height of the leveller it is essential to support the leveller base with plates or similar elements until the leveller is flush with the loading bay. The support points are those marked with the arrows in the following diagram:

Place at least the following levelling plates in position:

- 2 at the front of the machine (which must coincide with the weld cords).
- 3 at the rear of the machine which must coincide with the bedplate head pipes.
- 1 at each cylinder application point.

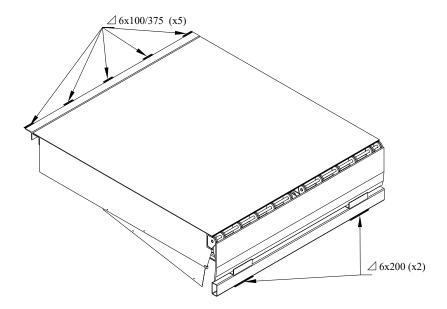
Then weld the plates to the leveller and weld the ramp to the recessing subframe, as indicated:

Block it against the wall, if necessary.



The weld areas are indicated in the following diagram:

- 2 weld cords with a throat of 6mm. and length of 200mm. coinciding with the points where the lip is supported on the front of the machine.
- 5 weld cords with a throat of 6 mm. and length of 100mm., distributed and separated by 375mm at the rear part.



05.02.02 - Securing in the case of a self-supporting model.

Once the leveller is in the pit, check the following:

The separation between the sides of the leveller and the pit must be exactly the same at the front and back of it.

In the event of the separation not being equal in the pit, this must be at the rear part and not at the sides.

These spacers have the mission of NOT allowing the sides of the bedplate to close against the mobile leveller, due to the pressure exerted when concreting the paving in the premises; if this should occur, it would cause a serious problem in the subsequent functioning of the machine.

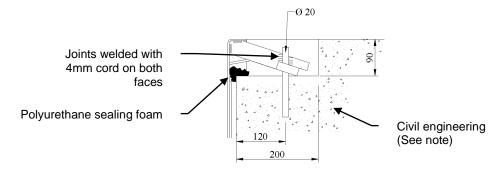
The anchoring hooks are in a pack supplied with the machine.

Distribute 5 hooks at the rear, 3 or 4 at each side (depending on the machine length) and 2 at each pipe at the front.

Weld one end to the profile of the bedplate and the other end to the reinforced concrete notch.

Weld one end to the profile of the bedplate and then seal the sides with polyurethane foam.

Once all the lips are welded, seal the sides with polyurethane foam so that the concrete cannot penetrate into the existing space. The platform will be ready for creating the formwork of the final paving in the loading bay.



Note: Floor of at least H250 concrete with a thickness greater than or equal to 200mm. Filling of perimeter with at least H250 concrete.

05.03 - Installing the electrical control panel

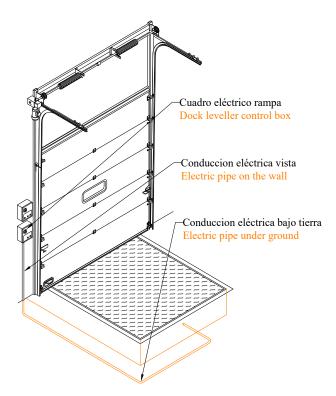
The electrical panel must be installed in the wall on the truck driver side, to allow the dock leveller operator to see and talk to the driver if necessary. (See electrical control panel connections, page 17)

Secure the electrical panel box to the wall at the desired height and perfectly aligned with the output of the leveller cables, approximately 1300mm from the floor.

Adjust the tube for the electrical cables to pass through at the existing distance between the panel and floor.

Secure the tube to the wall (using at least 3 brackets); it must be perpendicular to the loading bay floor and aligned with the leveller output cables.

The plastic tube is delivered sealed to one of the two sides of the leveller bedplate.



Once everything is secured, pass the cables through and connect, pursuant to the attached electrical diagram which is inside the electrical control panel. (See electrical control panel connections, page 17)

05.04 - Completed installation

Eliminate the front strips joining the lip to the bedplate.

VERY IMPORTANT: Weld the lateral panels, removing the rivet that holds them in place and check their movement and functionality.

Lastly, check the condition of the leveller paint, correcting any flaws (including the levelling plates).

The installation is considered completed when the installer authorised by **INKEMA** has filled in the respective installation control sheet.

05.05 - Electrical control panel connection

Before installing the automatisms, check that the power supply is disconnected

05.05.01 - Connecting the power input

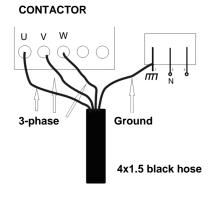
3-phase 220 V connection

MOTOR GUARD

L1
L2
L3
Ground

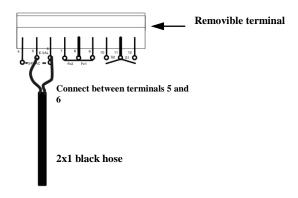
4x1.5 black hose

05.05.02 - Motor input connection



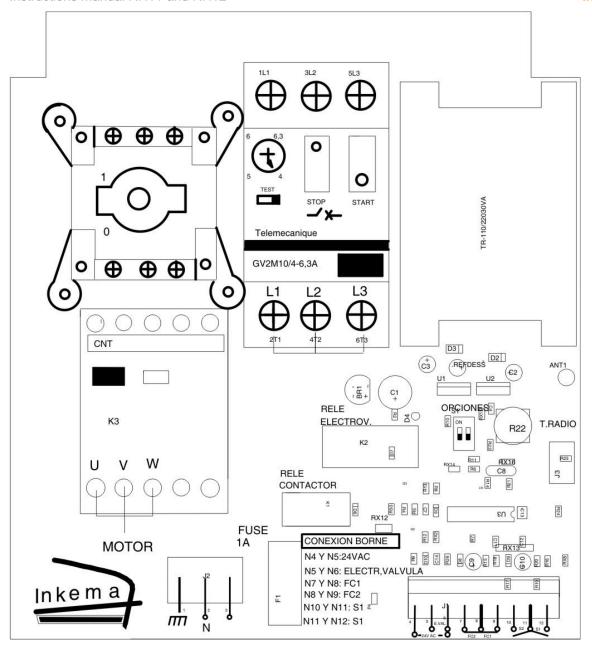
Note: check the rotation direction and change to the U-V-W motor output (if not correct)

05.05.03 - Electro valves connection



V03 – 2016 www.inkema.com 17

.



05.05.04 - Description of the connection terminals

- 1 Ground
- 2 Power input 220V ac
- 3 Power input 220V ac
- 4 Voltage 24V ac
- 5 Electro valve output 24V ac
- 6 Electro valve output 24V ac (24V ac power)
- 7 FC2 N.C. electro valve limit switch
- 8 Common Limit Switches
- 9 FC1 N.C. motor limit switch
- 10 S2 N.O. button (electro valve)
- 11 Common Push Buttons
- 12 S1 N.O. button (motor)

Note: N.O., Normally Open N.C., Normally Closed

05.05.05 - Actions Selection

Select the type of operation using the micro switches.



TABLE type Man present manual operation



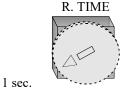
RH1 LEVELLER type semi-automatic operation



BAY WITH AUTOMATIC RETURN type semi-automatic operation.

05.05.06 - Timers

Leveller raising time. Regulates the automatic raising time when FC2 is activated.



15 sec.

05.05.07 - Operation

The automatism manoeuvres vary, depending on the type of operation selected.

a) TABLE type Man present manual operation

S1 activates the motor while pressed; electro valve deactivated.

S2 activates the electro valve when pressed; motor stopped.

FC1 deactivates the motor.

FC2 deactivates the electro valve.

b) RH1 LEVELLER type semi-automatic operation

S1 activates the motor while pressed; electro valve deactivated.

S2 deactivates the motor and the electro valve.

FC1 deactivates the motor.

FC2 deactivates the electro valve.

c) BAY WITH TIMED L.S., type semi-automatic operation.

S1 activates the motor while pressed; electro valve deactivated.

S2 deactivates the motor and the electro valve.

FC1 deactivates the motor.

FC2 activates the motor and deactivates the electro valve, when FC2 is deactivated, the motor continues operating during the time selected in **R. TIME** and the electro valve is activated, which will continue to be activated.

05.05.08 - Accessories

Radio Card.

Permits the use of a radio card for activating the automatism from the distance. This action is equivalent to pressing buttons S1 and S2.

RADIO C. connector

05.05.09 - Characteristics

Power supply

Fuse

Automatic Raising Rime
Radio Card

Operating Temperature

220V ac ±20%

1Amp.

1 sec. to 15 sec.

Optional

-20° C to +85°C

06 - Dismantling

06.01 - Dismantling an embedded leveller

VERY IMPORTANT: When handling the leveller, always respect the occupation risk prevention legislation and the regulations regarding safety, hygiene and health at work.

To dismantle the leveller, it must be in the rest position.

Disconnect from the mains and also disconnect the electrical panel. Dismantle the electrical panel box and electrical conduction tube.

Strap the front of the leveller to prevent it from opening when being handled. To do so, use at least 2 steel flanges of 30x1mm.

Then cut all the welding attaching the leveller to the subframe, at the front and back.

Once the above tasks have been completed, remove the leveller from the pit.

This operation should be made using a crane or similar element, using chains, slings or similar elements to raise it. With a load capacity equal to or greater than the weight of the leveller.

06.02 - Dismantling a self-supporting leveller

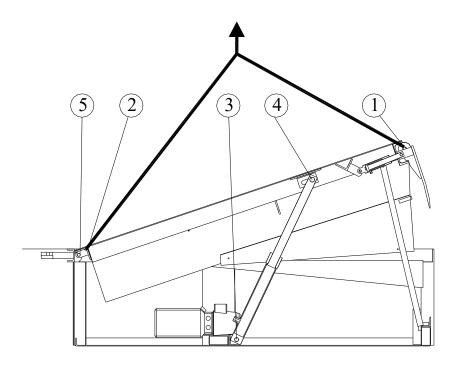
It is important to bear in mind that this type of leveller cannot be dismantled completely, as the bedplate is attached to the loading bay paving using formwork.

VERY IMPORTANT: When handling the leveller, always respect the occupation risk prevention legislation and the regulations regarding safety, hygiene and health at work.

Proceed as follows:

- With the leveller in the rest position, press the up/down button. The machine starts to rise. Just before the lip starts to open, press the emergency **STOP** button turning the selection switch to the (0) setting.
- In this position, release the maintenance bar and place it in the operating position.
- Connect the power and press the up/down button (once). Let the machine rest on the bar.
- Turn off the power.

VERY IMPORTANT: Check that the maintenance bar is in the correct position, as the dismantling work must be done inside the machine.



- As an additional safety measure, a sling will be placed on the platform as follows:
 - At the ends of the lip axle (1) to embrace the back part (2).
 - Use chains, slings or similar elements (with a load capacity equal to or greater than the weight of the leveller and keep under voltage, ensuring that the platform is not raised, so as not to block the maintenance lever.
 - This operation will be done using a crane or similar element, with a load capacity equal to or greater than the weight of the leveller.
- Disconnect from the mains and dismantle the electrical control panel and electrical conduction tube.
- Dismantle the elevation cylinders, including the bedplate bolts (3) and the platform bolts (4).
- Dismantle the hydraulic sleeves from the lip cylinders.
- Dismantle the rear hinge bolts (5).
- Once all the bolts have been dismantled, raise the platform.

07 - Incidents

Warning: All checks must be made taking the opportune safety measures:

- Do not perform checks when under voltage.
- Ensure which voltage is being measured with the multimeter.
- All cable connections and disconnections will be made when not under voltage.
- Put the safety bar in place whenever it is necessary to work underneath the machine.
- Do not test the machine when the operator is underneath it.

07.01 - The panel DOES NOT light up

No power	 Check the input voltage of the panel L1, L2, L3 and N There should be 400v between L1 and L3 There should be 400v between L2 and L3 There should be 230v between N and L1 Check that the motor guard has not fused - The black button is in and the red one out Check the voltage in the section switch L1, L2 and L3 - There must be 400v between L1 and L2 - There must be 400v between L1 and L3 - There must be 400v between L2 and L3 Check the voltage in the output of the section switch T1, T2 and T3 - There must be 400v between T1 and T2 - There must be 400v between T1 and T3 - There must be 400v between T2 and T3 Check the voltage in the contactor 1L1, 3L2 and 5L3 - There must be 400v between IL1 and 3L2
The panel does not light up	 There must be 400v between 1L1 and 5L3 There must be 400v between 3L2 and 5L3 A fuse has blown Check the red cable between contactor 1L1 and the block of connection terminal 3 Check the voltage between N and F in the terminal block (terminals 2 and 3) There must be 230v
A fuse has blown	 Crossover or failure in the electro valve Disconnect the electro valve cables terminals 5 and 6 Transformer burnt (transformer swollen or a smell of burning) Replace board Fault in the panel or damaged tracks Replace board

07.02 - The ramp DOES NOT rise

Voltage or phase failure	 Check the voltage between panel L1, L2 and L3 There should be 400v between L1 and L3 There should be 400v between L2 and L3 Check the voltage at the input of the section switch L1, L2 and L3 There should be 400v between L1 and L2 There should be 400v between L1 and L3 There should be 400v between L2 and L3 Check the voltage at the output of the section switch T1, T2 and T3 There should be 400v between T1 and T2 There should be 400v between T1 and T3 There should be 400v between T2 and T3 Check voltage in the contactor 1L1, 3L2 and 5L3 There should be 400v between 1L1 and 3L2 There should be 400v between 3L2 and 5L3 Check voltage at the output of the contactor in U, V and W There should be 400v between U and V There should be 400v between U and y W
	- There should be 400v between V and W
Guard motor shuts	 Low motor guard amperage Turn the amp adjustor in a clockwise direction to raise the amps to the nominal motor consumption (220v3R - 3'5A / 380v3R - 2A) Faulty cabling Disconnect cables of U, V and W of the contactor and Motor and check the cable continuities with the multimeter at each end of the cables Check the cables are not crossed, there must be no continuity between them. Position the multimeter between:
The motor DOES NOT work	 Check the panel U, V and W output voltage. - There must be 400v between U and V - There must be 400v between U and W - There must be 400v between V and W Check the motor cables and motor connections - There must be 400v between U and V - There must be 400v between U and W - There must be 400v between V and W Check that the motor has not seized up - Dismantle the fan housing and try turning it manually The contactor does not work - Check whether there is continuity in the push button - Check the terminal block connection (terminals 11 and 12) - Check the safety connection (terminals 8 and 9) If no safety device is installed, there must be a bridge connection between terminals 8 and 9 - If a safety device is connected, check that it is on NC (contact closed) - When operating as a table the raise table there is a limit switch, check that it is on NC Contactor relay damaged
	The motor is turning in reverse
The motor works	 Change 2 motor phases (U for V) Limit valve of power unit not correctly regulated Tighten the valve in quarter turns and check
	Replenish hydraulic oil
Lack of hydraulic oil	Hydraulic oil leak (rod or sleeve)

07.03 - The leveller DOES NOT descend

No voltage in the electro valve	 Check that PIN 1 is at ON (When functioning as a table PIN 1 must be at OFF) Check the safety device FC2 in terminals 7 and 8 If there is no safety device installed, there must be a bridge connection between terminals 7 and 8 If there is a safety device connected (when functioning as a table there is a foot protector device) check that it is on NC (contact closed) Check the output voltage in terminals 4 and 6 There must be 24v between terminals 4 and 6 Check that it is on NC (contact closed)
	 Check the output voltage in terminals 5 and 6 There must be 24v between terminals 5 and 6 after pressing once (the clear relay is blocked)
Electro valve	 Cabling cut Disconnect the cable from terminals 5 and 6 and from the electro valve. Check the continuity of the cables Check the input voltage in cowl 24v ~ Disconnect the cowl from the coil and check that the input voltage is 24v in alternating current and there is 24v at the output of the cowl in continuous current Electro valve coil Check the coil magnetising. Remove the coil from the sliding door and insert a screwdriver for a short interval of time, 2 or 3 seconds, under voltage. Very important: If placed there for longer the coil will be burned. Sliding door electro valve Check that when putting on and removing the electro valve cowl, the sliding door is activated and deactivated
Power unit	 Lowering adjuster too tight or too loose If the vale is too tight turn the screw in an anti-clockwise direction (loosen) If the valve is too loose, the piston safety valve could be triggered (tighten) Piston safety valve Dismantle the piston sleeve and connection fitting and check that the safety valve is not blocked

07.04 - The lip DOES NOT open or functions very slowly

Power unit	Sequence valve closed Turn the adjuster screw in an anti-clockwise direction (loosen) by quarter turns
Lip	Lip too stiff Dismantle the piston and check that the lip can move properly

07.05 - The lip opens before the leveller is raised

Downer unit	Sleeves mounted in reverse. Change the sleeves in the power unit
Power unit	The sequence valve has opened too much.

08 - Contact



Inkema Sistemas S.L

C/ Galileo, 2 – Naves 7 y 8 Apartado de correos 132 08150 Parets del Vallés Barcelona – (Spain)

GPS: N 41° 33′ 30" – E 02° 14′ 42"

Branches in Spain:

Tel: +34 93 544 47 08
Fax: +34 93 572 30 11
inkema@inkema.com
serviciotecnico@inkema.com

International distribution:

Tel: +34 93 544 47 08 <u>export@inkema.com</u>

Production centre in Rumania:

Str. Via Brescia esqu. ViaSperanza -307221

Chisoda – Timis – (Romania) Tel: 0040 256 215 819 Fax: 0040 256 215 818